

* Central difference interpolation formulae -
 As we know, Newton's forward and backward interpolation formulae are used to interpolate a value of x , ($x_0 \leq x \leq x_n$) for given set values at near the beginning and ending of the table set differences, respectively.

* Thus, the central difference formulae are most suitable for interpolation near the middle of a tabulated set. The central difference operator δ was already discussed in previous lecture.

The most important central difference formulae are ~~House~~, Stirling, Bessel and Everett. So, Gauss's formulae discussed below are of interest from a theoretical stand-point only.

Gauss's Forward Formula - We consider, the central ordinate (y_0) is taken for convenience according to $x = x_0$.

The differences used in the formula lie on the line shown in Gauss's Forward table.

The formula is of the form

$$y_p = y_0 + \omega_1 \Delta y_0 + \omega_2 \Delta^2 y_{-1} + \omega_3 \Delta^3 y_1 + \omega_4 \Delta^4 y_2 \dots \quad (1)$$

where b_1, b_2, \dots have to be determined.

The y_p of the left side can be expressed in terms of $y_0, \Delta y_0$ and higher-order differences of y_0 .

Table - Gauss's Forward Table.

x	y	Δ	Δ^2	Δ^3	Δ^4	Δ^5	Δ^6
x_{-3}	y_{-3}						
x_{-2}	y_{-2}	Δy_{-3}	$\Delta^2 y_{-3}$	$\Delta^3 y_{-3}$	$\Delta^4 y_{-3}$	$\Delta^5 y_{-3}$	$\Delta^6 y_{-3}$
x_{-1}	y_{-1}	Δy_{-2}	$\Delta^2 y_{-2}$	$\Delta^3 y_{-2}$	$\Delta^4 y_{-2}$	$\Delta^5 y_{-2}$	$\Delta^6 y_{-2}$
x_0	y_0	Δy_{-1}	$\Delta^2 y_{-1}$	$\Delta^3 y_{-1}$	$\Delta^4 y_{-1}$	$\Delta^5 y_{-1}$	$\Delta^6 y_{-1}$
x_1	y_1	Δy_0	$\Delta^2 y_0$	$\Delta^3 y_0$	$\Delta^4 y_0$	$\Delta^5 y_0$	$\Delta^6 y_0$
x_2	y_2	Δy_1	$\Delta^2 y_1$	$\Delta^3 y_1$	$\Delta^4 y_1$	$\Delta^5 y_1$	$\Delta^6 y_1$
x_3	y_3	Δy_2	$\Delta^2 y_2$	$\Delta^3 y_2$	$\Delta^4 y_2$	$\Delta^5 y_2$	$\Delta^6 y_2$

Diagram illustrating the forward and backward differences in Gauss's Forward Table. The table shows values for x from x_{-3} to x_3 and y from y_{-3} to y_3 . The differences are calculated as follows:

- Forward differences: $\Delta y_0, \Delta^2 y_0, \Delta^3 y_0, \Delta^4 y_0, \Delta^5 y_0, \Delta^6 y_0$
- Backward differences: $\Delta y_{-1}, \Delta^2 y_{-1}, \Delta^3 y_{-1}, \Delta^4 y_{-1}, \Delta^5 y_{-1}, \Delta^6 y_{-1}$

Arrows indicate the direction of calculation: "Back." for backward differences and "forw." for forward differences.

So, clearly $y_p = E^p y_0$ where $E = (1 + \Delta) \Rightarrow$ shift oper.

$$y_p = (1 + P)^p y_0$$

$$y_p = y_0 + p \Delta y_0 + \frac{p(p-1)}{2!} \Delta^2 y_0 + \dots$$

Similarly, the right side of $E^h(P)$ can be expressed in terms of $y_0, \Delta y_0$ and higher-order differences.

$$\Delta^2 y_1 = \Delta^2 E^{-1} y_0$$

We know

$$\Delta^2 y_{-1} = \Delta^2 E^{-1} y_0$$

$$= \Delta^2 (1 + P)^{-1} y_0$$

$$= \Delta^2 (1 - \Delta + \Delta^2 - \Delta^3 + \dots) y_0$$

$$= \Delta^2 (y_0 - \Delta y_0 + \Delta^2 y_0 - \Delta^3 y_0 + \dots)$$

$$\Delta^2 y_{-1} = \Delta^2 y_0 - \Delta^3 y_0 + \Delta^4 y_0 - \Delta^5 y_0 + \dots$$

Then $\Delta^3 y_{-1} = \Delta^3 y_0 - \Delta^4 y_0 + \Delta^5 y_0 - \Delta^6 y_0 + \dots$

$$\Delta^4 y_{-2} = \Delta^4 E^{-2} y_0$$

$$= \Delta^4 (1 + \Delta)^{-2} y_0$$

$$= \Delta^4 (1 - 2\Delta + 3\Delta^2 - 4\Delta^3 + \dots) y_0$$

$$= \Delta^4 y_0 - 2\Delta^5 y_0 + 3\Delta^6 y_0 - 4\Delta^7 y_0 + \dots$$

Hence, $\mathcal{E}_p^n (i)$ gives the identity

$$y_0 + p \Delta y_0 + \frac{p(p-1)}{L_2} \Delta^2 y_0 + \dots$$

$$= y_0 + \omega_1 \Delta y_0 + \omega_2 (\Delta^2 y_0 - \Delta^3 y_0 + \Delta^4 y_0 - \dots)$$

$$+ \omega_3 (\Delta^3 y_0 - \Delta^4 y_0 + \Delta^5 y_0 - \dots)$$

$$+ \omega_4 (\Delta^4 y_0 - 2\Delta^5 y_0 + 3\Delta^6 y_0 - 4\Delta^7 y_0 + \dots)$$

$$+ \dots \quad (ii)$$

Equating the coefficients of $\Delta y_0, \Delta^2 y_0, \Delta^3 y_0, \dots$ etc. on both side in $\mathcal{E}_p^n (ii)$

$$\omega_1 = p, \quad \omega_2 = \frac{p(p-1)}{L_2}, \quad \omega_3 = \frac{(p+1)p(p-1)}{L_3},$$

$$\omega_4 = \frac{(p+1)p(p-1)(p-2)}{L_4}, \dots$$

Similarly for -

Gauss's Backward Formula → This formula

uses the differences ~~with~~ which lie on the line (dashed) shown in table.

Gauss's backward formula can be assumed to be of the form.

$$y_p = y_0 + b_1' \Delta y_{-1} + b_2' \Delta^2 y_{-1} + b_3' \Delta^3 y_{-2} + b_4' \Delta^4 y_{-2} + \dots$$

Where b_1', b_2', b_3', \dots have to be determined. Following the same procedure as in Gauss's forward formula, we obtain -

$$b_1' = p, \quad b_2' = \frac{p(p+1)}{L_2}, \quad b_3' = \frac{p(p+1)(p-1)}{L_3}$$

$$b_4' = \frac{(p+2)(p+1)p(p-1)}{L_4}, \dots$$

Stirling's formula - Taking mean of Gauss's

forward and backward formulae, we obtain

$$y_p = y_0 + p \frac{\Delta y_{-1} + \Delta y_0}{2} + \frac{p^2}{2} \Delta^2 y_{-1} + \frac{p(p^2-1)}{L_3} \frac{(\Delta^3 y_{-1} + \Delta^3 y_{-2})}{2} + \frac{p^2(p^2-1)}{L_4} \Delta^4 y_{-2} + \dots$$

This is called Stirling's formula.